Madiyar Mukanov

MSc Robotics graduate passionate about intelligent perception, real-time control and human-centric robots

Education

2023–2025 M.Sc. Robotics, Satbayev University, Almaty

(exp.) **Thesis**: Intelligent System for Automated Patient Monitoring via Thermal Imaging Key coursework: Advanced Robotics Control, Machine Vision, Embedded Real-Time Systems

2017–2022 B.Sc. Nuclear Physics, Al-Farabi Kazakh National University, Almaty Thesis: Static correlation properties of thermonuclear plasma (HNC method)

Technical Skills

Robotics ROS, OpenCV, Raspberry Pi

& CV

Programming Python, C++, C#, MATLAB, Git

Embedded / Raspberry Pi, ESP32-CAM, I²C/SPI/UART

HW

AI / Data PyTorch, TensorFlow Lite, cycleGAN

CAD & Sim COMSOL Multiphysics

Tools Linux, SQLite, ModelSim, Quartus

Robotics Experience

2023- Research Engineer, Robotics & Mechatronics Lab, Satbayev University, Almaty

Present \odot Designed thermal-vision module (Pi Camera 2 + MLX90640 overlay) achieving $\pm 1\,^{\circ}\text{C}$ accuracy; integrated face-tracking.

Temperature records to SQLite

Mar 2025 Research Intern, Shanghai Jiao Tong University, Shanghai

- O Participated in an academic visit, exploring 3D research labs and industrial robotics facilities.
- Attended TCT Asia 2025 gaining insights into emerging technologies and industry trends.

Summer 2019 Research Trainee (Sakura Science), Kyoto Institute of Technology, Kyoto

- O Participated in an international 4-member team project focused on smart mobility solutions.
- O Designed and built a bicycle-mounted speedometer using embedded sensors and microcontrollers.

Dec 2020- Backend Developer (Contributor), Kazakhstan Pavilion, EXPO Dubai 2021, Dubai

Jan 2021 Contributed to backend development of a mobile application featured at the Kazakhstan Pavilion.

Selected Projects

- Thermal-Vision Telehealth Camera full-stack Python/Linux app with Matplotlib UI and DB logging.
- 2019 Autonomous Bicycle Speedometer 1st place, International Competition in Electronics.
- 2021 **Plasma Simulation Toolkit** Investigated radial distribution function (RDF) and static structure factor (SSF) for the BIM (Binary Ionic Mixture) model using the HNC (Hypernetted Chain) approximation; presented at Farabi Alemi conference.

Additional Research

Surface modification via PECVD and plasma etching; maintained vacuum lab equipment.

Awards & Leadership

2019 Award for Excellence in Electronics, Kyoto (1st place) 3rd place, Student Business Incubator Pitch, Almaty

2017–2022 Full Academic Scholarship, Al-Farabi KazNU

Languages

Kazakh (native) • Russian (native) • English (IELTS 7.0) • Arabic (beginner)